ISTITUTO LOMBARDO

ACCADEMIA DI SCIENZE E LETTERE

RENDICONTI

Scienze Matematiche e Applicazioni

A

Vol. 125 (1991) - Fasc. 2

ESTRATTO

CARLO FELICE MANARA e MARIO MARCHI

ON A CLASS OF REFLECTION GEOMETRIES

Istituto Lombardo Accademia di Scienze e Lettere MILANO

1992

ON A CLASS OF REFLECTION GEOMETRIES

Nota del m. e. CARLO FELICE MANARA e MARIO MARCHI (*)

(Adunanza del 10 ottobre 1991)

SUNTO. – In questa Nota si introduce un sistema di assiomi che permette di caratterizzare una particolare classe di geometrie di riflessione. Tali geometrie consistono di uno spazio di incidenza (detto anche spazio lineare o spazio di rette) con parallelismo dotato di un insieme transitivo di dilatazioni involutorie e di un insieme regolare di traslazioni. Esse risultano quindi anche rappresentabili mediante una opportuna classe di cappi di incidenza.

Introduction

By a reflection we usually understand an involutory movement in an absolute plane with a pointwise fixed line. As a matter of fact it is well known the possibility to define in an abstract way an absolute space by means of a group Γ provided with a set of involutory elements fulfilling suitable axioms. The group Γ is named reflection group (Spiegelungsgruppe) and reflection geometry (Spiegelungsgeometrie) is the geometric structure defined in this way (see e.g. [2], [4]).

^(*) This research is supported partially by the Italian Ministry of University and Scientific and Technological Research (M.U.R.S.T.) (40% and 60% grants) and by G.N.S.A.G.A of C.N.R.

In this paper we shall be concerned with a different notion of "reflection" which could be thought as a generalization of the classical notion of point-reflection in an absolute plane. This notion of reflection is introduced in an abstract way by means of suitable axioms (A1)-(A4) stated for any arbitrary set \mathcal{P} of elements, named points (cf. § 1). Our aim is to provide the point set \mathcal{P} with a *line structure* \mathcal{L} which could be consistent with the reflection axioms. This will be obtained by means of a new set of axioms: (D1)-(D3); in this way (\mathcal{P}, \mathcal{L}) turns out to be an *incidence space* (cf. e.g. [3], [4]) (*linear space* or *line space* in other Authors) and furthermore in \mathcal{L} a parallelism relation can be defined (§ 2). The reflections defined by the axioms (A1)-(A4) give rise to a set of involutory dilatations and a transitive set of translations for the space ($\mathcal{P}, \mathcal{L}, \mathscr{I}$) (§ 3). This allow us to provide the incidence space ($\mathcal{P}, \mathcal{L}, \mathscr{I}$) whit a structure of *incidence loop with parallelism* which is unique up to isomorphisms (§ 4).

1. - Existence of reflections

Let \mathcal{O} be a set of elements, which henceforth we shall call *points*. Let us assume for each point $a \in \mathcal{O}$ a bijection $\tilde{a} : \mathcal{O} \longrightarrow \mathcal{O}$; $x \longrightarrow \tilde{a}(x)$ is defined such that the following axioms are fulfilled:

A1. $\forall x \in \mathcal{O} : \tilde{x}(x) = x;$ A2. $\forall a, b, x \in \mathcal{O}, a \neq b \implies \tilde{a}(x) \neq \tilde{b}(x);$ A3. $\forall a \in \mathcal{O} : \tilde{a}^2 := \tilde{a} \cdot \tilde{a} = id;$ A4. $\forall x, y \in \mathcal{O} = a \in \mathcal{O} : \tilde{a}(x) = y.$

Henceforth these bijections will be called *reflections*. In the following we shall always denote by "id" the identity map and by "o" the composition of mappings. Thus we have:

1.1. - Let a, b, x, y be any points of \mathfrak{P} ; then: (i) $x \neq a \implies \tilde{a}(x) \neq x$;

(ii) if for some $z \in \mathcal{O}$ it is $\tilde{a}(z) = \tilde{b}(z)$, then a = b;

(iii) if $\tilde{a}(x) = y$, then $\tilde{a}(y) = x$.

(i) By (A2) and (A1): $a \neq x \implies \tilde{a}(x) \neq \hat{x}(x) = x$.

(ii) If $a \neq b$ by (A2) we have for any $x \in \mathcal{P} \tilde{a}(x) \neq \tilde{b}(x)$ which is a contradiction.

(iii) Immediate by (A3).

From (1.1, ii) it follows immediately:

1.2. - For any $x, y \in \mathcal{O}$, the element $a \in \mathcal{O}$ which exists by (A4) is uniquely determined.

If we denote $\tilde{\Theta} := \{\tilde{a} : a \in \Theta\}$, let us define:

$$\mathcal{C} := \tilde{\mathcal{P}} \circ \tilde{\mathcal{P}} := \{ \tilde{a} \circ \tilde{b} : a, b \in \mathcal{P} \} .$$

By (A3) $id \in \mathfrak{C}$. Then:

1.3. - (i) For each $\tau \in \mathbb{C} \setminus \{id\}, \forall x \in \mathcal{P} \text{ we have: } \tau(x) \neq x;$ (ii) \mathbb{C} acts transitively on \mathcal{P} .

PROOF. - (i) Let us suppose $y \in \mathcal{O}$ such that $\tau(y) = y$. Then if we denote $\tau := \tilde{a} \circ \tilde{b}$, we have $\tilde{a} \circ \tilde{b}(y) = y$ which implies $\tilde{a}(y) = \tilde{b}(y)$, by (A3), and thus by (1.1, ii) $\tilde{a} = \tilde{b}$ i.e. $\tau = id$, which is a contradiction.

(ii) For any $x, y \in \mathcal{O}$, by (A1) and (A4) there exists $a \in \mathcal{O}$ such that $\tilde{a}(x) = \tilde{a} \circ \tilde{x}(x) = y$.

1.4. - The following conditions are equivalent:

- (i) \mathcal{C} acts regularly on \mathcal{O} ;
- (ii) $\tilde{\Theta} \circ \tilde{\Theta} \circ \tilde{\Theta} \subseteq \tilde{\Theta};$
- (iii) **Co**C = C;
- (iv) & is a group.

PROOF. -

(i) \implies (ii). By assumption for any $\tau_1, \tau_2 \in \mathbb{C}$ and for any $x \in \mathcal{O}$, $\tau_1(x) = \tau_2(x)$ implies $\tau_1 = \tau_2$. For any $\tilde{a}_1, \tilde{a}_2, \tilde{a}_3 \in \tilde{\mathcal{O}}$, if x is any point

of \mathcal{O} , let us denote \tilde{c} the reflection, uniquely determined by (A4) and (1.2) such that $\tilde{c}(\tilde{a}_3(x)) = \tilde{a}_1 \circ \tilde{a}_2(x)$. Then by assumption $\tilde{c} \circ \tilde{a}_3 = \tilde{a}_1 \circ \tilde{a}_2$ and hence by (A3) $\tilde{a}_1 \circ \tilde{a}_2 \circ \tilde{a}_3 = \tilde{c} \circ \tilde{a}_3 \circ \tilde{a}_3 = \tilde{c} \in \tilde{\mathcal{O}}$.

(ii) \implies (iii). Since $id \in \mathbb{C}$ we have: $\mathbb{C} \subseteq \mathbb{C} \circ \mathbb{C}$. If $\bar{a}_1 \circ \hat{b}_1$, $\bar{a}_2 \circ \bar{b}_2$ are any mappings of \mathbb{C} , by (ii) there exists $\bar{c} \in \tilde{\mathcal{O}}$ such that $(\bar{a}_1 \circ \bar{b}_1) \circ \circ (\bar{a}_2 \circ \bar{b}_2) = (\bar{a}_1 \circ \bar{b}_1 \circ \bar{a}_2) \circ \bar{b}_2 = \bar{c} \circ \bar{b}_2 \in \mathbb{C}$; thus $\mathbb{C} \circ \mathbb{C} \subseteq \mathbb{C}$.

(iii) \implies (iv). By (A3), for any $(\tilde{a} \circ \tilde{b}) \in \mathfrak{F}$ we have $(\tilde{b} \circ \tilde{a}) = (\tilde{a} \circ \tilde{b})^{-1}$; thus by (iii) and since $id \in \mathfrak{F}, \mathfrak{F}$ is a group.

(iv) \implies (i). For any $\tau_1, \tau_2 \in \mathbb{C}$ and any $x \in \mathcal{O}, \tau_1(x) = \tau_2(x)$ implies $\tau_2^{-1} \circ \tau_1(x) = x$. Since by assumption $\tau_2^{-1} \circ \tau_1 \in \mathbb{C}$ and by (1.3, i) $\tau_2^{-1} \circ \tau_1 = id$, it follows $\tau_1 = \tau_2$ and thus because of the transitivity, \mathbb{C} is regular on \mathcal{O} .

1.5. - If & is a group, then it is commutative.

PROOF. - For any \tilde{a}_1 , \tilde{a}_2 , $\tilde{a}_3 \in \tilde{\mathcal{O}}$, by (1.4, ii) and (A3), $\tilde{a}_1 \circ \tilde{a}_2 \circ \tilde{a}_3$ is involutory and then $\tilde{a}_1 \circ \tilde{a}_2 \circ \tilde{a}_3 = \tilde{a}_3 \circ \tilde{a}_2 \circ \tilde{a}_1$. Thus for any $\tilde{a}_1 \circ \tilde{b}_1$, $\tilde{a}_2 \circ \tilde{b}_2 \in \mathfrak{S}$ we have $\tilde{a}_1 \circ \tilde{b}_1 \circ \tilde{a}_2 \circ \tilde{b}_2 = \tilde{a}_2 \circ \tilde{b}_1 \circ \tilde{a}_1 \circ \tilde{b}_2 = \tilde{a}_2 \circ \tilde{b}_2 \circ \tilde{a}_1 \circ \tilde{b}_1$; thus \mathfrak{S} is commutative.

2. - The line structure

In $\mathfrak{O} \times \mathfrak{O}$ an equivalence relation Δ is defined fulfilling the following axioms:

D1. $\forall a, b, c \in \mathcal{O} : (a, b) \Delta (c, c) \iff a = b;$ D2. $\forall a, x, y \in \mathcal{O} : (x, y) \Delta (\tilde{a} (x), \tilde{a} (y));$ D3. $\forall a, b, x \in P$, distinct: $(a, x) \Delta (x, b) \iff (a, x) \Delta (a, b).$

2.1. - For any $a, b, c \in \mathcal{O}$ we have:

i) $(a, b) \Delta (b, a);$

- ii) $(a, c) \Delta (a, \tilde{a} (c));$
- iii) $\tilde{c}(a) = b \implies (a, c) \Delta(c, b)$ and $(a, c) \Delta(a, b)$.

(i) Let us denote $d \in \mathcal{O}$ the uniquely determined point, by (A4) and (1.2), such that $\tilde{d}(a) = b$ and then $\tilde{d}(b) = a$. Thus by (D2) $(a, b) \Delta(\tilde{d}(a), \tilde{d}(b)) = (b, a)$.

(ii) Follows from (D2) and (A1).

(iii) Follows from (D2), (i) and (D3).

Let us define for any $a, b \in \mathcal{P}$, $a \neq b$:

(1)
$$\overline{a, b} := \{x \in \mathcal{O} : (a, x) \Delta (a, b)\} \cup \{a\}.$$

Of course, by definition is $a, b \in \overline{a, b}$; furthermore we have:

2.2. For any $a, b \in \mathcal{O}$, $a \neq b$, it is: $\overline{a, b} \setminus \{a, b\} \neq \emptyset$.

PROOF. - By (A4) it exists $c \neq a, b$ such that $\tilde{c}(a) = b$; then, by (2.1, iii): $(a, c) \Delta(a, b)$ that is $c \in \overline{a, b} \setminus \{a, b\}$.

2.3. For any $a, b \in \mathcal{O}$, $a \neq b : \overline{a, b} = \overline{b, a}$.

PROOF. - By (D3), $\forall x \in \overline{a}, \overline{b} \setminus [a, b] : (a, x) \Delta (a, b)$ implies (a, x) $\Delta (x, b)$; then by (2.1, i) and since Δ is transitive it is $(b, x) \Delta (b, a)$ and thus $x \in \overline{b}, \overline{a}$. Furthermore $a, b \in \overline{b}, \overline{a}$ by definition. Therefore $\overline{a, b} \subseteq \overline{b, a}$, and with the same arguments: $\overline{b, a} \subseteq \overline{a, b}$.

2.4. - For any $c \in \overline{a, b} \setminus \{a\} : \overline{a, c} = \overline{a, b}$.

PROOF. By definition $\forall x \in \overline{a, b} \setminus [a] : (a, x) \Delta (a, b) \Delta (a, c)$ implies $x \in \overline{a, c}, b \in \overline{a, c}$ i.e. $\overline{a, b} \subseteq \overline{a, c}$. With the same argument, since $b \in \overline{a, c} \setminus [a] : \overline{a, c} \subseteq \overline{a, b}$.

2.5. - For any $c, e \in \overline{a, b}, c \neq e : \overline{c, e} = \overline{a, b}$.

PROOF. If c = a, the theorem is proved by (2.4). $c \in \overline{a, b} \setminus \{a\}$ implies by (2.4) $\overline{a, b} = \overline{a, c}$; then again by (2.4) $e \in \overline{a, b} \setminus \{c\} = \overline{c, a} \setminus [c]$ implies $\overline{c, a} = \overline{c, e}$.

The set of points $\overline{a, b}$ will be called the line $\overline{a, b}$. By (2.4) we have $|\overline{a, b}| \ge 3$.

The set of all lines defined by (1) will be denoted by \mathcal{L} and thus the pair $(\mathcal{P}, \mathcal{L})$ turns out to be an *incidence space*. For any $a, b, c \in \mathcal{P}, a \neq b$ let us define:

(2)
$$\{c \not\mid \overline{a, b}\} := [x \in \mathcal{P} : (c, x) \Delta (a, b)] \cup [c]$$

2.6. - $\{c \not | \overline{a, b}\}$ is a line and $[c \not | \overline{a, b}] = \overline{a, b}$ when $c \in \overline{a, b}$.

PROOF. -

(i) If c = a the definition (2) coincides with (1). If $c \in \overline{a, b} \setminus [a]$, by definition for any $x \in [c \neq \overline{a, b}] \setminus \{c\}$ we have $(a, c) \Delta(a, b) \Delta(c, x)$ and thus $(c, x) \Delta(c, a)$ which implies $\{c \neq \overline{a, b}\} = \overline{c, a} = \overline{a, b}$, because of (2.4).

(ii) Let us suppose $c \notin \overline{a, b}$; by (A4) there exists a point u such that $\tilde{u}(a) = c$. Then by (D2) $\forall x \in \{c \not a, b\} \setminus \{c\} : (c, x) \Delta(a, b) \Delta(c, \tilde{u}(b));$ hence by denoting $e := \tilde{u}(b)$ we have $(c, x) \Delta(a, b) \Delta(c, e)$ and thus by definition (1): $\{c \not a, b\} = \overline{c, e}$.

Because of (2.2) and (2.6) we have proved that $|[c \not/ \overline{a, b}]| \ge 3$; thus $\forall (a, b) \in \mathcal{O}^2$, $\forall c \in \mathcal{O}$ there exists at least one point e such that $(c, e) \Delta (a, b)$.

2.7. For any $e \in \{c \not\mid \overline{a, b}\}$ we have $[e \not\mid \overline{a, b}] = \{c \not\mid \overline{a, b}\}$.

PROOF. If $\{c \not\mid \overline{a, b}\} = \overline{a, b}$ by (2.6) we have $\{e \not\mid \overline{a, b}\} = \overline{a, b}$. If e = c the statement is trivial. Then let us suppose $e \neq c$ and $c \notin \overline{a, b}$. By definition $e \in [c \not\mid \overline{a, b}] \setminus [c]$ implies $(c, e) \Delta (a, b)$; then $\forall x \in \{c \not\mid \overline{a, b}\} \setminus [c]$: $(c, x) \Delta (a, b) \Delta (c, e)$ and by (D3) if $x \neq e(c, x) \Delta (c, e)$ implies $(c, x) \Delta (x, e)$. Thus $(e, x) \Delta (a, b)$ and hence $x \in [e \not\mid \overline{a, b}]$, i.e. $\{c \not\mid \overline{a, b}\} \subseteq [e \not\mid \overline{a, b}]$.

Since $c \in [e \neq \overline{a, b}]$, with the same arguments we have also $[e \neq \overline{a, b}] \subseteq [c \neq \overline{a, b}]$, and thus $\{e \neq \overline{a, b}\} = \{c \neq \overline{a, b}\}$.

REMARK I. - Because of (2.7) we have, for any $a, b, c, d \in \mathcal{O}$, with $a \neq b : [c \neq \overline{a}, \overline{b}] \cap [d \neq \overline{a}, \overline{b}] \neq \emptyset$ implies $\{c \neq \overline{a}, \overline{b}\} = \{d \neq \overline{a}, \overline{b}\}$; in fact if $e \in [C \neq \overline{a}, \overline{b}] \cap \{d \neq \overline{a}, \overline{b}\}$, by (2.7) we have: $\{c \neq \overline{a}, \overline{b}\} = [e \neq \overline{a}, \overline{b}\} = [d \neq \overline{a}, \overline{b}]$.

For any two lines $\overline{a, b}, \overline{c, d}, \in \mathcal{L}$ let us now define:

$$\overline{a, b} \not \sim \overline{c, d} \iff (a, b) \Delta (c, d)$$
.

Since Δ is an equivalence relation, \mathscr{V} is also an equivalence relation. Furthermore, because of (2.6), for any $\overline{a, b} \in \mathfrak{L}$ and any $c \in \mathcal{O}$ there exists a line $L \in \mathfrak{L}$ such that $c \in L$ and $L \not\subset \overline{a, b}$. Actually we have $L := \lfloor c \not\subset \overline{a, b} \rfloor$. Moreover by (2.7) this line L is unique. Thus " \mathscr{V} " is an equivalence relation defined in \mathfrak{L} which fulfils the Euclidean axiom; " \mathscr{V} " will be called *parallelism* and the triple ($\mathcal{O}, \mathfrak{L}, \mathscr{V}$) turns out to be an *incidence space with parallelism*.

3. - The reflection geometry

We can now study some properties of an incidence space with parallelism endowed with a set of reflections as defined in § 1.

3.1. - For any L ∈ L and a ∈ 𝔅 we have:
(i) ã (L) ∈ L and ã (L) ≠ L;
(ii) ã (L) = L ⇔ a ∈ L.

PROOF. -

(i) Let be $L = : \overline{u, v} = [x \in \mathcal{O} : (u, x) \Delta (u, v)] \cup [u];$ then $\tilde{a}(L) = [\tilde{a}(x) : (u, x) \Delta (u, v)] \cup [\tilde{a}(u)]$ and since by (D2) $(u, x) \Delta (\tilde{a}(u), \tilde{a}(x))$, by denoting $y := \tilde{a}(x)$ we have by (2) : $\tilde{a}(L) = \{y \in \mathcal{O} : (\tilde{a}(u), y) \Delta (u, v)\} \cup [\tilde{a}(u)\} = \{\tilde{a}(u) \not \in \mathcal{L}\}$.

(ii) " \Leftarrow " If $a \in L = : \overline{u, v}(u, a) \Delta(u, v)$ implies by (D2) $(\tilde{a}(u), a) \Delta \Delta(u, v)$ i.e. $a \in [\tilde{a}(u) \not (\overline{u, v}] = \tilde{a}(L)$ and thus $\tilde{a}(L) = L$ because of the Remark I, § 2.

" \implies " Let $L = : \overline{u, v}$; by (D2) $(u, a) \Delta(a, u) \Delta(a, \bar{a}(u))$ which implies, by (D3): $(u, a) \Delta(u, \bar{a}(u))$. Furthermore $\bar{a}(L) = |\bar{a}(u) \vee L| =$ $= L = \overline{u, v}$ implies $\bar{a}(u) \in \overline{u, v}$ and thus $(u, \bar{a}(u)) \Delta(u, v)$. Hence we have $(u, a) \Delta(u, v)$ which means $a \in \overline{u, v}$. By (3.1) we have proved the following situation.

 $(\mathcal{O}, \mathcal{L}, \mathscr{I})$ is an incidence space with parallelism where the set of reflections $\tilde{\mathcal{O}} := \{\tilde{a} : a \in \mathcal{O}\}$ is a set of involutory dilatations, acting transitively on \mathcal{O} because of (A4).

Such an incidence space with the set $\tilde{\Theta}$ of dilatations fulfilling the axioms (A1)-(A4) will be denoted henceforth by $(\mathcal{O}, \mathcal{L}, \mathscr{I}, \tilde{\Theta})$ and will be called a *point-reflection geometry*.

Furthermore by (1.3) $\mathfrak{T} := \mathfrak{O} \circ \mathfrak{O} = [\mathfrak{a} \circ \mathfrak{b} : \mathfrak{a}, \mathfrak{b} \in \mathfrak{O}]$ is a set of translations acting transitively on \mathfrak{O} . Henceforth we shall denote by $\mathfrak{D} := Aut(\mathfrak{O}, \mathfrak{L}, \mathscr{A})$ the group of all dilatations of $(\mathfrak{O}, \mathfrak{L}, \mathscr{A})$ and by \mathfrak{K} the set of all translations, i.e. fixed-point-free dilatations, of $(\mathfrak{O}, \mathfrak{L}, \mathscr{A})$ together with the identity map "id".

Now, by denoting $u \in \mathcal{O}$ a distinguished point, let us define

$$\mathbb{C} := \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{u}} = \{ \tilde{a} \circ \tilde{\mathfrak{u}} : a \in \mathfrak{O} \} .$$

Thus C is a set of translations acting regularly on \mathcal{O} . In fact $\forall x, y \in \mathcal{O}$, since by (A4) it exists $c \in \mathcal{O}$ such that $\tilde{c}(y) = \bar{u}(x)$ we have $\tilde{c} \cdot \tilde{u}(x) = y$ and thus C is transitive.

Furthermore if $\tilde{c} \circ \tilde{u}(x) = \tilde{e} \circ \tilde{u}(x)$ we have, by denoting $z := \tilde{u}(x)$, $\tilde{c}(z) = \tilde{e}(z)$ which implies, by (1.1, ii) $\tilde{c} = \tilde{e}$. Furthermore we have: $id \in \mathbb{C}$.

3.2. - The set \mathfrak{T} is a group if and only if $\mathfrak{C} = \mathfrak{T}$.

PROOF. - " \implies " By definition $\mathbb{C} \subseteq \mathbb{C}$. On the other hand for any $\bar{a} \circ \bar{b} \in \mathbb{C}$, if $c \in \mathbb{C}$ is the point, uniquely determined by (A4), such that $\tilde{c}(u) = \bar{a} \circ \tilde{b}(u)$, we have by (1.4, i): $\tilde{a} \circ \tilde{b} = \bar{c} \circ \bar{u}$ and then $\mathbb{C} \subseteq \mathbb{C}$.

" \Leftarrow " By definition C is acting regularly on \mathcal{O} and thus by (1.4) \mathfrak{T} is a group.

3.3. - In $(\mathfrak{O}, \mathfrak{L}, \mathscr{A}, \tilde{\mathfrak{O}})$ the followings hold:

i) for any three non collinear points a, b, c the parallelogram configuration holds, i.e.: $|b \sqrt[a]{a,c}| \cap \{c \sqrt[a]{a,b}\} \neq \emptyset$; furthermore in any parallelogram (a, b, c, x) the diagonal lines do meet;

ii) if $\delta \in Aut(\mathfrak{O}, \mathfrak{L}, \mathscr{M}) \setminus \{id\}$ with $\delta^2 = id$, then $\delta \in \tilde{\mathfrak{O}}$.

(i) Let $u \in \mathcal{O}$ be the point, uniquely determined by (A4), such that $\tilde{u}(b) = c$. Then $\tilde{u}(\overline{a, c}) = \{b \not / \overline{a, c}\}, \ \overline{u}(\overline{a, b}) = [c \not / \overline{a, b}] \text{ and so } \{x\} : = [\tilde{u}(a)] = [b \not / \overline{a, c}] \cap [c \not / \overline{a, b}] \neq \emptyset$ since \tilde{u} is a bijection on \mathcal{O} . Thus $|u| = \overline{a, x} \cap \overline{b, c}$.

(ii) Let $a \in \mathcal{P}$ be any point with $\delta(a) \neq a$ and $b := \delta(a)$. For any $x \in \mathcal{P} \setminus \overline{a, b}$ we have $\delta(x) := \delta(\overline{a, x} \cap \overline{b, x}) = \{b \not| \overline{a, x}\} \cap \{a \not| \overline{b, x}\}$, and $\delta(x)$ does exist since δ is a bijection. If $u \in \mathcal{P}$ is the point, uniquely determined by (A4), such that $\tilde{u}(a) = b$, by (i) we have $\bar{u}(x) = \delta(x)$ and thus, since δ and \tilde{u} are dilatations, $\delta = \bar{u}$.

REMARK I. - As a consequence of (3.3, ii), in $(\mathcal{O}, \mathfrak{L}, \mathbb{A}, \overline{\mathcal{O}})$ do not exist involutory translations.

Because of (3.3, i) the following configurational proposition (T) holds in any point-reflection geometry $(\mathfrak{O}, \mathfrak{L}, \mathscr{I}, \tilde{\mathfrak{O}})$.

3.4. - For any three non collinear points $a_1, a_2, a_3 \in \mathcal{O}$ there exist three non collinear points b_1, b_2, b_3 such that (configuration T):

 $[b_3] := [a_1 \not < \overline{a_2, a_3}] \cap [a_2 \not < \overline{a_1, a_3}] \neq \emptyset;$ $[b_1] := [a_2 \not < \overline{a_1, a_3}] \cap [a_3 \not < \overline{a_1, a_2}] \neq \emptyset;$ $[b_2] := [a_3 \not < \overline{a_1, a_2}] \cap [a_1 \not < \overline{a_2, a_3}] \neq \emptyset.$

The triangle Tr (a_1, a_2, a_3) is said to be *inscribed* in Tr (b_1, b_2, b_3) and furthermore Tr (a_1, a_2, a_3) and Tr (b_1, b_2, b_3) are said to be *similar*. By (3.4) we know that any triangle Tr (a_1, a_2, a_3) can be inscribed in a similar one but we don't know if, vice versa, any triangle Tr (b_1, b_2, b_3) can circumscribe a similar one.

By definition we know that $\mathfrak{T} := \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \subseteq \mathfrak{K} \subseteq \mathfrak{D}$ and, since $id \in \mathfrak{T}, \tilde{\mathfrak{O}} \subseteq \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \subseteq \mathfrak{D}$. What in general we don't know is whether (for any $a, b, c \in \mathfrak{O}$) the dilatation $\tilde{a} \circ \tilde{b} \circ \tilde{c}$ has one fixed point or not. In other words it is not known whether in a general point-reflection geometry $(\mathfrak{O}, \mathfrak{L}, \mathscr{I}, \tilde{\mathfrak{O}})$ it is $\tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \cap \mathfrak{K} = \emptyset$ or not. Furthermore if $\tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \circ \tilde{\mathfrak{O}} \cap \mathfrak{K} = \emptyset$, the proper dilatation $\tilde{a} \circ \tilde{b} \circ \tilde{c}$ (for any $a, b, c \in \mathfrak{O}$) can be involutory or not.

When $\hat{a} \circ \tilde{b} \circ \tilde{c}$ is involutory (for any $a, b, c \in \mathcal{P}$) we have by (3.3, ii): $\tilde{\mathcal{P}} \circ \tilde{\mathcal{P}} \circ \tilde{\mathcal{P}} \subseteq \tilde{\mathcal{P}}$ and thus $\tilde{\mathcal{P}} \circ \tilde{\mathcal{P}} \circ \tilde{\mathcal{P}} = \tilde{\mathcal{P}}$. In this case by (1.4) \mathfrak{T} is a commutative group.

3.5. Let $a_1, a_2, a_3 \in \mathcal{O}$ be non collinear and such that $\delta := \bar{a}_1 \circ \bar{a}_2 \circ \bar{a}_3$ is a proper dilatation; let us denote by x the fixed points of δ . Then three points $b_1, b_2, b_3 \in \mathcal{O}$ are uniquely determined such that, for any permutation (i, j, h) of (1, 2, 3), it holds:

 $a_i \in \overline{b_j, b_h}$, $b_h := \tilde{a}_i (b_j)$, $b_2 := x$;

this implies also:

$$\tilde{a}_{i} \circ \tilde{a}_{i} \circ \tilde{a}_{h} (b_{i}) = b_{i}$$

PROOF. $\tilde{a}_1 \circ \tilde{a}_2 \circ \tilde{a}_3(x) = x$ implies $\tilde{a}_2 \circ \tilde{a}_3(x) = \tilde{a}_1(x)$; thus by denoting $b_1 := \tilde{a}_3(x)$, $b_2 := x$, $b_3 := \tilde{a}_1(x)$ we have $\tilde{a}_2(b_1) = b_3$ and, by (D2) and the definition (1) of line, $a_i \in \overline{b_j}, \overline{b_h}$.

REMARK II. - The triangle Tr (a_1, a_2, a_3) defined in (3.5) is inscribed in Tr (b_1, b_2, b_3) ; Tr (b_1, b_2, b_3) will be said the *fixed-points-triangle* for the triple of reflections $\{\bar{a}_1, \bar{a}_2, \bar{a}_3\}$. Now by (3.3) let us denote by $\{c_i\} := \{b_j \not \sim \overline{b_i}, \overline{b_b}\} \cap \{b_h \not \sim \overline{b_i}, \overline{b_j}\}$; then the triangle Tr (c_1, c_2, c_3) circumscribes the similar triangle Tr (b_1, b_2, b_3) . Hence, since by (3.3, i) $\bar{a}_i (b_j) = b_h$ implies also $\bar{a}_i (c_i) = b_i$, we have:

$$\tilde{a}_i \circ \tilde{a}_j \circ \tilde{a}_h (c_h) = c_i$$
.

Using the same notations of (3.5) and Remark II, we can now state the following propositions. Actually (3.6) and (3.7) follow immediately from (3.5) and (A4).

3.6. - For any $a_1, a_3, x \in \mathcal{O}$ non collinear, one point $a_2 \in \mathcal{O}$ is uniquely determined such that $\tilde{a}_1 \circ \tilde{a}_2 \circ \tilde{a}_3(x) = x$.

3.7. - For any $b_1, b_2, b_3 \in \mathcal{O}$ non collinear. a triple of reflections $\{\tilde{a}_1, \tilde{a}_2, \tilde{a}_3\}$ admitting Tr (b_1, b_2, b_3) as the fixed-points-triangle is uniquely determined.

3.8. - For any $b_1, b_2, b_3 \in \mathcal{P}$ non collinear, if Tr (b_1, b_2, b_3) is the fixed-points-triangle for a triple of reflections $[\tilde{a}_1, \tilde{a}_2, \tilde{a}_3]$, Tr (a_1, a_2, a_3) is inscribed and similar to Tr (b_1, b_2, b_3) if and only if \mathfrak{T} is a group.

PROOF. . " \leftarrow " By (1.5) the group \mathfrak{T} is commutative. In this case we know (cfr. [1]) that, for any $\tau \in \mathfrak{T}$ and for any $x \in \mathcal{O}$, $L \in \mathfrak{L}$, $L \not = \overline{x}, \tau(\overline{x})$ implies $\tau(L) = L$. With the notations of (3.5) we have $\tilde{a}_i \circ \tilde{a}_h(b_i) = b_h$ and $\tilde{a}_i \circ \tilde{a}_h \in \mathfrak{T}$; hence $\bar{a}_i \circ \tilde{a}_h(\overline{b_i}, \overline{b_h}) = [b_h / / \overline{b_i}, \overline{b_h}] = \overline{b_i}, \overline{b_h}$. Otherwise $\tilde{a}_i \circ \tilde{a}_h(a_h) = \tilde{a}_i(a_h) \in \overline{a_i}, \overline{a_h}$ implies $\tilde{a}_i \circ \tilde{a}_h(\overline{a_i}, \overline{a_h}) = \overline{a_i}, \overline{a_h}$. Thus $\overline{b_i}, \overline{b_h} / \overline{a_i}, \overline{a_h}$.

" \Longrightarrow " Again with the notations of (3.5) and Remark II we have: $\tilde{a}_{h} \circ \tilde{a}_{i} (b_{h}) = b_{i}$ and $\tilde{a}_{h} \circ \tilde{a}_{i} (b_{j}) = c_{h}$. By assumption b_{1}, b_{2}, b_{3} are any three non collinear points and $\tau := \tilde{a}_{h} \circ \tilde{a}_{i} \in \mathfrak{T}$ is a translation of \mathfrak{T} mapping b_{h} onto b_{i} and b_{j} onto c_{h} . Then τ fulfils the law of parallelograms i.e. $[\tau (b_{j})] = [b_{j} / \overline{b_{i}}, \overline{b_{h}}] \cap \{b_{i} / \overline{b_{j}}, \overline{b_{h}}\}$ and then acts regularly on \mathcal{O} ; this implies by (1.4) that \mathfrak{T} is a group. \Box

Let now L be any line. We shall denote $\tilde{L} := \{\tilde{a} \in \tilde{\Theta} : a \in L\},\$ $\mathfrak{S}_{L} := \tilde{L} \circ \tilde{L} = \{\tilde{a} \circ \tilde{b} : a, b \in L\}.$

By (3.1) we have $\tilde{L}(L) = L$ and $\mathfrak{C}_{L}(L) = L$. Thus $\tilde{L} \circ \tilde{L} \circ \tilde{L}$ is a set of dilatations with the possible fixed point on L.

By (1.4), since the axioms (A1)-(A4) are independent from the axioms of the line structure we have:

3.9. - Let L be any line of a point-reflection geometry ($\mathfrak{O}, \mathfrak{L}, \mathscr{I}, \tilde{\mathfrak{O}}$). Then the following conditions are equivalent:

- i) \mathfrak{S}_{L} acts regularly on L;
- ii) $\tilde{L} \circ \tilde{L} \circ \tilde{L} = \tilde{L};$
- iii) \mathfrak{S}_{L} is a group.

4. - The associated incidence loop

It is well known (see e.g. [5]) that an incidence space with parallelism ($\mathcal{O}, \mathcal{L}, \mathscr{N}$) together with a regular set of translations S can be represented as an incidence loop in the following way.

If 1 is a distinguished point of \mathcal{O} , for any point $a \in \mathcal{O}$ let us denote a^{\bullet} the uniquely determined translation $a^{\bullet} \in S$ such that $a^{\bullet}(1) = a$. Then we can define in \mathcal{O} a composition low " \bullet " by denoting for any $a, b \in \mathcal{O}, a \cdot b := a^{\bullet}(b) = a^{\bullet} \circ b^{\bullet}(1)$; in this way $(\mathcal{O}, \mathcal{L}, \mathscr{I}, \bullet)$ turns out to be an *incidence loop with parallelism* (cf. [3] and [5]). In the present situation, we can assume $S := \mathcal{O}$ and for the sake of semplicity 1 := u. As a consequence for any $a \in \mathcal{O}$, if we denote $a_m \in \mathcal{O}$ the point, uniquely determined by (A4) and (1.2), such that $\bar{a}_m(u) = a$, we shall have:

$$a^{\bullet} := \tilde{a}_{\mathbf{m}} \circ \tilde{u} ;$$

and, for any $a, b \in \mathcal{O}$:

(4)
$$a \cdot b := a^{\bullet}(b) = a^{\bullet} \circ b^{\bullet}(u) = \tilde{a}_{\mathfrak{m}} \circ \tilde{u} \circ \tilde{b}_{\mathfrak{m}}(u) = (\tilde{a}_{\mathfrak{m}} \circ \tilde{u})(b)$$

Then with the usual notations (cfr. [3]) we shall represent by (\mathcal{O}, \cdot) the set \mathcal{O} of points endowed with the loop structure defined in (3), by $\mathfrak{L} := \{aL : a \in \mathcal{O}, u \in L \in \mathfrak{L}\}$ the set of lines and by the condition:

$$aL \not = bM \iff L = M$$

the parallelism relation between nay two lines $aL, bM \in \mathcal{L}$. Furthermore the left multiplication in (\mathcal{P}, \cdot) will represent the translations of the set \mathcal{C} . The incidence loop with parallelism $(\mathcal{P}, \mathcal{L}, \mathscr{I}, \cdot)$ defined in this way from the reflection geometry $(\mathcal{P}, \mathcal{L}, \mathscr{I}, \tilde{\mathcal{P}})$ will be called *incidence loop with reflections* and will be denoted by $(\mathcal{P}, \mathcal{L}, \mathscr{I}, \cdot, \cdot)$.

4.1. - Let $(\mathfrak{O}, \mathfrak{L}, \mathscr{A}, \bullet, \sim)$ be an incidence loop with reflections as previously defined. The following properties hold.

i) CoC ⊆ °;

ii) $\forall a \in \mathcal{O} \exists a^{-1} \in \mathcal{O}$ such that: $a^{-1}a = aa^{-1} = u$;

iii) $\forall a \in \mathcal{O} : (a^{\bullet})^{-1} = (a^{-1})^{\bullet}$; then $\mathbb{C}^{-1} = \mathbb{C}$;

iv) $\forall a \in \mathcal{O} : \tilde{u}(a) = a^{-1};$

v) $\forall a \in \mathcal{O} : \tilde{a}(u) = a^2$.

(i) Let be $\tilde{a} \circ \tilde{u}$, $\tilde{b} \circ \tilde{u} \in \mathbb{C}$. Since $(\tilde{u} \circ \tilde{b} \circ \tilde{u})$ $(\tilde{u} \circ \tilde{b} \circ \tilde{u}) = id$, the dilatation $\tilde{u} \circ \tilde{b} \circ \tilde{u}$ is involutory and thus by (3.3, ii) it exists $c \in \mathcal{O}$ with $\tilde{c} := \tilde{u} \circ \tilde{b} \circ \tilde{u}$; this implies $\tilde{a} \circ \tilde{u} \circ \tilde{b} \circ \tilde{u} = \tilde{a} \circ \tilde{c} \in \mathfrak{C}$.

(ii) By [6] and [7] it will be enough to prove that, for any $\alpha, \beta \in \mathbb{C}$, $\alpha \circ \beta(u) = u$ implies $\beta \circ \alpha(u) = u$. Actually let us denote $\alpha := \bar{a}_{m} \circ \tilde{u}$, $\beta := \bar{b}_{m} \circ \bar{u}$; then $u = \alpha \circ \beta(u) = \tilde{a}_{m} \circ \tilde{u} \circ \bar{b}_{m} \circ \tilde{u}(u) = \tilde{a}_{m} \circ \tilde{u} \circ \tilde{b}_{m}(u)$ implies $\bar{b}_{m} \circ \tilde{u} \circ a_{m}(u) = u$. Then $\beta \circ \alpha(u) = \bar{b}_{m} \circ \tilde{u} \circ \bar{a}_{m} \circ \tilde{u}(u) = \bar{b}_{m} \circ \tilde{u} \circ \tilde{a}_{m}(u) = u$ and thus by [6] (proposition 1.2) or [7] (proposition 4, § 2) it exists a^{-1} .

(iii) By definition and by (ii) we have $a \cdot a^{-1} = a^{\bullet} (a^{-1}) = u$ which implies $a^{-1} = (a^{\bullet})^{-1} (u)$. Otherwise, again by definition, $a^{-1} = (a^{-1})^{\bullet} (u)$; then $(a^{\bullet})^{-1} (u) = (a^{-1})^{\bullet} (u)$ that is $a^{\bullet} \circ (a^{-1})^{\bullet} (u) = u$. By (i) $a^{\bullet} \circ (a^{-1})^{\bullet} \in \mathfrak{S}$ which implies $a^{\bullet} \circ (a^{-1})^{\bullet} = id$, i.e. $(a^{-1})^{\bullet} = (a^{\bullet})^{-1}$. By (ii) $\mathcal{O}^{-1} = \mathcal{O}$ and thus $\mathcal{C}^{-1} = \mathcal{C}$.

(iv) Since $\tilde{u}, a^* \in \mathfrak{D}, \tilde{u}(a) = \tilde{u} \circ a^* (u) = \tilde{u} \circ \tilde{a}_m \circ \tilde{u}(u)$. Furthermore $\tilde{u} \circ \tilde{a}_m = (\tilde{a}_m \circ \tilde{u})^{-1} = (a^*)^{-1} = (a^{-1})^*$. Then: $\tilde{u}(a) = (a^{-1})^* \circ \tilde{u}(u) = a^{-1}$.

(v) Let us consider the dilatation $\delta := a^{\bullet} \circ \tilde{u} \circ (a^{\bullet})^{-1}$; since $\delta(a) = a^{\bullet} \circ \tilde{u} \circ (a^{\bullet})^{-1}(a) = a^{\bullet} \circ \tilde{u}(u) = a$ and $\delta \circ \delta = id$, by (A1), (A2) and (3.3, ii) we have $\delta = \tilde{a}$. Then by (iii) and (iv) $\tilde{a}(u) = \delta(u) = a^{\bullet} \circ \tilde{u} \circ (a^{\bullet})^{-1}(u) = a^{\bullet} \circ \tilde{u} \circ (a^{-1})^{\bullet}(u) = a^{\bullet} \circ \tilde{u}(a^{-1}) = a^{\bullet}(a) = a^{2}$.

REMARK I. - In (4.1, i) we have proved that, for any $\tilde{b} \in \tilde{\mathcal{O}}$ we have $\tilde{u} \circ \tilde{b} \circ \tilde{u} \in \tilde{\mathcal{O}}$. By denoting $\bar{c} := \tilde{u} \circ \tilde{b} \circ \tilde{u}$ we obtain $c = \tilde{c}(c) = \tilde{u} \circ \tilde{b} \circ \tilde{u}(c)$, i.e. $\tilde{u}(c) = \tilde{b} \circ \tilde{u}(c)$. Then, by (A1) and (A2) $\tilde{u}(c) = b$, and by (4.1, iv) $c = b^{-1}$. Hence $(\tilde{a} \circ \tilde{u}) \circ (\tilde{b} \circ \tilde{u}) = \tilde{a} \circ \tilde{c} = \tilde{a} \circ (\tilde{b}^{-1})$.

REMARK II. - By (4.1, v) we know that, for any $b \in \mathcal{O}$, $\tilde{b}(u) = b^2$. By (A4) and (1.2), for any $a \in \mathcal{O}$, it exists a unique $a_m \in \mathcal{O}$ such that $\tilde{a}_m(u) = a$ and in this way we have defined a^{\bullet} by (3). Then by denoting $b := a_m$ we can see that for any $a \in \mathcal{O}$ it exists the square root "b" i.e. $b \in \mathcal{O}$ such that $b^2 = a$.

4.2. - Let $(\mathfrak{O}, \mathfrak{L}, \mathscr{I}, \bullet)$ be an incidence loop with parallelism fulfilling the following conditions:

i) if 1 denotes the unitary element of (\mathcal{O}, \cdot) , for any $a \in \mathcal{O}$ there exists $a^{-1} \in \mathcal{O}$ such that $a \cdot a^{-1} = a^{-1} \cdot a = 1$;

ii) there exists a dilatation $\omega \in Aut (\mathfrak{O}, \mathfrak{L}, \mathscr{A}) \setminus [id]$ such that $\omega(1) = 1$, $\omega^2 = id$ and, for any $a \in \mathfrak{O}, \omega(a) = a^{-1}$;

iii) for any $x, y \in \mathcal{P}$ there exists a unique solution "a" for the equation

(5)
$$(a^{-1}x)(a^{-1}y) = 1$$
.

Then a set of reflections $\wedge : \mathfrak{O} \longrightarrow \mathfrak{O}$; $a \longrightarrow \hat{a}$ can be defined fulfilling the axioms (A1)-(A4) such that $(\mathfrak{O}, \mathfrak{L}, \mathscr{V}, \hat{\mathfrak{O}})$ is a point-reflection geometry.

PROOF. - For any $a \in \mathcal{O}$ let us define: $\hat{a} := a^{\circ} \circ \omega (a^{\circ})^{-1}$; since a° is a translation for $(\mathcal{O}, \mathfrak{L}, \mathscr{A})$, $(a^{\circ})^{-1} \in Aut(\mathcal{O}, \mathfrak{L}, \mathscr{A})$ and thus $\hat{a} \in Aut(\mathcal{O}, \mathfrak{L}, \mathscr{A})$. Since by definition $a = a^{\circ} (1)$ implies $(a^{\circ})^{-1} (a) = 1$, we have $\hat{a} (a) = a^{\circ} \circ \omega \circ (a^{\circ})^{-1} (a) = a^{\circ} \circ \omega (1) = a$ and thus (A1) is fulfilled. Furthermore by $\hat{a} \circ \hat{a} = a^{\circ} \circ \omega \circ (a^{\circ})^{-1} \circ a^{\circ} \circ \omega \circ (a^{\circ})^{-1} = id$, (A3) is fulfilled too. Since $1^{\circ} = id$ we have also $\omega = \hat{1}$. In order to prove the axioms (A2) and (A4) we have to compare $(a^{\circ})^{-1}$ and $(a^{-1})^{\circ}$. By the definition of a° we have $(a^{\circ})^{-1} (a) = 1$ and, by (i), $a^{\circ} (a^{-1}) = 1$ implies $(a^{\circ})^{-1} (1) = a^{-1}$; furthermore by (i) we have $(a^{-1})^{\circ} \in Aut(\mathcal{O}, \mathfrak{L}, \mathscr{A})$ we have $(a^{\circ})^{-1} = (a^{-1})^{\circ}$.

Let us now consider, for any $x, y \in \Theta$ the condition $\hat{a}(x) = y$: this is equivalent to $a^{\bullet} \circ \omega \circ (a^{\bullet})^{-1}(x) = y$ i.e. $\omega \circ (a^{\bullet})^{-1}(x) = (a^{\bullet})^{-1}(y)$. By the properties of ω and $(a^{\bullet})^{-1}$ we have $(a^{\bullet})^{-1}(y) = (a^{-1})^{\bullet}(y) = a^{-1}y$ and $\omega \circ (a^{\bullet})^{-1}(x) = (a^{-1}x)^{-1}$. Then $\hat{a}(x) = y$ gives rise to the equation (5) which has a unique solution $a \in \Theta$; thus (A2) and (A4) are fulfilled. Furthermore, since $\hat{\Theta} := [\hat{a} : a \in \Theta] \subseteq Aut(\Theta, \mathfrak{L}, \mathbb{A})$, the axiom (D2) is fulfilled, while (D3) is a consequence of the existence of lines and parallelism. \Box

REMARK III. - Let us suppose in the loop (\mathcal{O}, \cdot) the property L.I.P. (*left inverse property*; cf. [7]) holds, i.e. for any $a, b \in \mathcal{O}$: $a^{-1}(a \cdot b) = (a^{-1} \cdot a) b$.

Then the existence of solutions for the equation (5) implies the existence of square roots for any element of (\mathcal{O}, \bullet) . Actually by assuming x := 1, for any $y \in \mathcal{O}$, the solution "a" of (5) is such that $a^{-1} [a^{-1} (a \cdot a)] = a^{-1} [(a^{-1} \cdot a) \cdot a] = 1$, i.e. $y = a^2$.

REMARK IV. - Let us now suppose that incidence loop $(\mathcal{O}, \mathfrak{L}, \mathscr{I}, \bullet)$ considered in (4.2) is provided as well with a set of reflections $\tilde{\mathcal{O}}$ which means it is an *incidence loop with reflections* $(\mathcal{O}, \mathfrak{L}, \mathscr{I}, \bullet, \sim)$. By (3.3, ii) we know that, for any $a \in \mathcal{O}$, $\hat{a} \in \tilde{\mathcal{O}}$; thus, since $\hat{a}(a) = a$, by (A2) we have $\hat{a} = \tilde{a}$; hence $(\mathcal{O}, \mathfrak{L}, \mathscr{I}, \bullet, \sim)$ and $(\mathcal{O}, \mathfrak{L}, \mathscr{I}, \bullet, \wedge)$ are isomorphic.

REFERENCES

- [1] J. ANDRE, Über Parallelstrukturen, II. Math. Z.; 76 (1961), 155-163.
- [2] F. BACHMANN, Aufbau der Geometrie aus dem Spiegelungsbegriff, Springer Verlag, Berlin, Göttingen. Heidelberg, 1959.
- [3] H. KARZEL, G.P. KIST, Kinematic Algebras and their Geometries, Ring and Geometry (Kaya et al. editors). Nato ASI Series C, vol. 160 (1985), 437-509.
- [4] H. KARZEL, K. SORENSEN, D. WINDELBERG, Einführung in die Geometrie, Vandenhoeck & Ruprecht, Göttingen, 1973.
- [5] M. MARCHI, Configurations in Incidence Loops, J.C.I.S.S., 15 (1990), 287-300.
- [6] M. MARCHI, Incidence Loops and their Geometry, COMBINATORICS '90; Proceedings of the conference on Combinatorics, Gaeta, Italy, 20-27 May, 1990; (Barlotti et al. editors). North Holland (1992), 347-364.
- [7] E. ZIZIOLI, Fibered Incidence Loops and Kinematic Loops, Journal of Geometry, 30 (1987), 144-156.

